

# SPDEs with fractional noise in space with index $H < 1/2$

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Barcelona Probability Seminar  
22 d'octubre de 2014

# Outline

- Stochastic wave and heat equations with spatially homogeneous noise
- Motivation, objective and strategy
- Stochastic integration
- Picard iteration scheme
- Some references

# Stochastic heat and wave equations

We consider the **stochastic wave equation**:

$$\left\{ \begin{array}{l} \frac{\partial^2 u}{\partial t^2}(t, x) = \Delta u(t, x) + \sigma(u(t, x))\dot{X}(t, x), \quad t \in [0, T], x \in \mathbb{R}^d \\ u(0, x) = u_0(x), \quad \frac{\partial u}{\partial t}(0, x) = v_0(x), \end{array} \right. \quad (\text{SWE})$$

and the **stochastic heat equation**:

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t}(t, x) = \frac{1}{2} \Delta u(t, x) + \sigma(u(t, x))\dot{X}(t, x), \quad t \in [0, T], x \in \mathbb{R}^d \\ u(0, x) = u_0(x) \end{array} \right. \quad (\text{SHE})$$

- $\Delta$  denotes the **Laplacian** operator on  $\mathbb{R}^d$ .
- $\sigma : \mathbb{R} \rightarrow \mathbb{R}$  is a **Lipschitz** function,
- $u_0, v_0 : \mathbb{R} \rightarrow \mathbb{R}$  are **bounded** and **Hölder** continuous,
- $\dot{X}(t, x)$  is a **spatially homogeneous Gaussian** noise.

# Spatially homogeneous Gaussian noise

On some probability space  $(\Omega, \mathcal{F}, \mathbb{P})$ , let  $X = \{X(\varphi), \varphi \in \mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d)\}$  be a **zero-mean Gaussian process** with

$$\mathbb{E}[X(\varphi)X(\psi)] = \int_0^\infty \Gamma(\varphi(t, \cdot) * \tilde{\psi}(t, \cdot)) dt$$

- $\mathcal{D}(\mathcal{O})$ : functions in  $\mathcal{C}^\infty(\mathcal{O})$  with compact support.
- $\Gamma$  is a **non-negative-definite tempered distribution** on  $\mathbb{R}^d$ .
- $\tilde{\psi}(t, x) = \psi(t, -x)$ ,  $(t, x) \in \mathbb{R}_+ \times \mathbb{R}^d$ .
- The Lebesgue integral in  $t$  means that the process is **white** in time.
- There exists a **tempered measure**  $\mu$  on  $\mathbb{R}^d$  such that  $\mathcal{F}\mu = \Gamma$  in the space  $\mathcal{S}'(\mathbb{R}^d)$  of tempered distributions on  $\mathbb{R}^d$ .

$$\mathbb{E}[X(\varphi)X(\psi)] = \int_0^\infty \int_{\mathbb{R}^d} \mathcal{F}\varphi(t, \cdot)(\xi) \overline{\mathcal{F}\psi(t, \cdot)(\xi)} \mu(d\xi) dt$$

The **spectral measure**  $\mu$  satisfies

$$\int_{\mathbb{R}^d} \left( \prod_{j=1}^d \frac{1}{1 + \xi_j^2} \right) \mu(d\xi) < \infty \quad \left[ \iff \int_{\mathbb{R}^d} \frac{1}{1 + |\xi|^2} \mu(d\xi) < \infty \right]$$

In order to solve SPDEs, one aims to construct **stochastic integrals** with respect to  $X$ .

**Remark:** the process  $X = \{X(\varphi), \varphi \in \mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d)\}$  defines a **stationary random distribution** (Itô 1954, Yaglom 1957). That is,

$$\mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d) \ni \varphi \mapsto X(\varphi) \in L^2(\Omega)$$

is linear and continuous, and the covariance is invariant under translations:

$$\mathbb{E}[X(\tau_h \varphi) X(\tau_h \psi)] = \mathbb{E}[X(\varphi) X(\psi)] \quad \text{for any } h \in \mathbb{R}_+ \times \mathbb{R}^d.$$

## Mild solutions

Fix  $T > 0$ . A random field  $\{u(t, x), (t, x) \in [0, T] \times \mathbb{R}^d\}$  is a **solution** of (SWE) (resp. (SHE)), if it is predictable and, for any  $(t, x) \in [0, T] \times \mathbb{R}^d$ ,

$$u(t, x) = w(t, x) + \int_0^t \int_{\mathbb{R}^d} G_{t-s}(x - y) \sigma(u(s, y)) X(ds, dy) \quad \text{a.s.}$$

where  $G_t(x)$  denotes the corresponding **fundamental solution**: e.g., for  $d = 1$  we have

$$G_t(x) = \frac{1}{2} \mathbf{1}_{\{|x| < t\}} \quad (\text{wave}), \quad G_t(x) = \frac{1}{(2\pi t)^{1/2}} \exp\left(-\frac{|x|^2}{2t}\right) \quad (\text{heat})$$

and  $w(t, x)$  is the contribution of the **initial data**:

$$w(t, x) = \frac{1}{2} \int_{x-t}^{x+t} v_0(y) dy + \frac{1}{2} (u_0(x+t) + u_0(x-t)) \quad (\text{wave}),$$
$$w(t, x) = \int_{\mathbb{R}} G_t(x - y) u_0(y) dy \quad (\text{heat})$$

## Motivation and objective

**Recall:** for any  $\varphi, \psi \in \mathcal{D}(\mathbb{R}_+ \times \mathbb{R}^d)$ ,

$$\mathbb{E}[X(\varphi)X(\psi)] = \int_0^\infty \Gamma(\varphi(t, \cdot) * \tilde{\psi}(t, \cdot)) dt = \int_0^\infty \int_{\mathbb{R}^d} \mathcal{F}\varphi(t, \cdot)(\xi) \overline{\mathcal{F}\psi(t, \cdot)(\xi)} \mu(d\xi) dt$$

Most results in the literature assume the following:

**(A)**  $\Gamma$  is a non-negative-definite tempered **measure** (or in particular,  $\Gamma$  is a non-negative **locally integrable function**  $f$ ).

In this case,

$$\begin{aligned} \mathbb{E}[X(\varphi)X(\psi)] &= \int_0^\infty \int_{\mathbb{R}^d} (\varphi(t, \cdot) * \tilde{\psi}(t, \cdot))(x) \Gamma(dx) dt \\ &= \int_0^\infty \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \varphi(t, x) f(x - y) \psi(t, y) dy dx dt. \end{aligned}$$

Under assumptions **(A)** and

$$\int_{\mathbb{R}^d} \frac{1}{1 + |\xi|^2} \mu(d\xi) < \infty, \quad (1)$$

Dalang 1999 (also Dalang and Q-S 2011) proved **existence of a unique solution** to a general class of SPDEs in  $\mathbb{R}^d$  including:

- (i) (SWE) with  $d \in \{1, 2, 3\}$ ,
- (ii) (SHE) for any  $d \geq 1$ .

On the other hand, Peszat and Zabczyk 2007 obtained existence and uniqueness of a **function-space valued** solution to (i) and (ii) under condition (1) and

**(B)** There exists a constant  $C > 0$  such that  $\Gamma + C\lambda_d$  is a non-negative measure, where  $\lambda_d$  is the Lebesgue measure on  $\mathbb{R}^d$ .



As far as (SWE) in any  $d \geq 3$  is concerned:

- Peszat 2002 (**function-space valued** solution): assumption **(B)** and

$$\sup_{\eta \in \mathbb{R}^d} \int_{\mathbb{R}^d} \frac{1}{1 + |\xi - \eta|^2} \mu(d\xi) < \infty. \quad (2)$$

He proved that, under **(B)**, (2) is equivalent to (1).

- Dalang and Mueller 2003 (**hybrid** approach): assumption **(A)** and condition (1).
- Conus and Dalang 2008 (**random field** solution): assumption **(A)** and condition (2).

In all these results, the involved **stochastic integral** can be interpreted as a stochastic integral with respect to a **martingale measure** (or **cylindrical Wiener process**): e.g. Walsh 1986, Da Prato and Zabczyk 1992, Dalang 1999, Dalang and Q-S 2011.

From now on, assume  $d = 1$ , and consider the following **important example**:

- Assume that the space correlation behaves like a **fractional Brownian motion** with  $H \in (0, 1)$ .
- This corresponds to take a **spectral measure**  $\mu$  of the form

$$\mu(d\xi) = c_H |\xi|^{1-2H} d\xi, \quad \text{with} \quad c_H = \frac{\Gamma(2H + 1) \sin(\pi H)}{2\pi}$$

- The measure  $\mu$  satisfies (1) for all  $H \in (0, 1)$ .
- But condition (2) does **not** hold for  $H < 1/2$ .
- In fact, if  $H > 1/2$ ,  $\Gamma = \mathcal{F}\mu$  is the locally integrable **function**  $f(x) = H(2H - 1)|x|^{2H-2}$ , which satisfies **(A)**.
- But if  $H < 1/2$ ,  $\Gamma = \mathcal{F}\mu$  is a genuine **distribution** (Jolis 2010):

$$\Gamma(\varphi) = H(2H - 1) \int_{\mathbb{R}} (\varphi(x) - \varphi(0)) |x|^{2H-2} dx, \quad \varphi \in \mathcal{D}(\mathbb{R})$$

**Objective:** consider the **stochastic wave and heat equations**

$$\left\{ \begin{array}{l} \frac{\partial^2 u}{\partial t^2}(t, x) = \frac{\partial^2 u}{\partial x^2}(t, x) + \sigma(u(t, x))\dot{X}(t, x), \quad t \in [0, T], x \in \mathbb{R} \\ u(0, x) = u_0(x), \quad \frac{\partial u}{\partial t}(0, x) = v_0(x), \end{array} \right. \quad (\text{SWE})$$

and

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t}(t, x) = \frac{1}{2} \frac{\partial^2 u}{\partial x^2}(t, x) + \sigma(u(t, x))\dot{X}(t, x), \quad t \in [0, T], x \in \mathbb{R} \\ u(0, x) = u_0(x) \end{array} \right. \quad (\text{SHE})$$

where we assume that

- $\sigma(z) = az + b$  is an **affine** function,
- $\dot{X}(t, x)$  is a spatially homogeneous Gaussian noise with **spectral measure**  $\mu(d\xi) = c_H |\xi|^{1-2H} d\xi$  with  $H \in (\frac{1}{4}, \frac{1}{2})$ .
- $u_0, v_0 : \mathbb{R} \rightarrow \mathbb{R}$  are **bounded** and  **$H$ -Hölder** continuous,

Under the above hypotheses, we aim to prove the following. Assume that  $H \in (\frac{1}{4}, \frac{1}{2})$ .

## Theorem

Equation (SWE) (respectively (SHE)) has a unique solution  $u = \{u(t, x), (t, x) \in [0, T] \times \mathbb{R}\}$ , which is  $L^2(\Omega)$ -continuous and satisfies, for any  $p \geq 2$ ,

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \mathbb{E}[|u(t, x)|^p] < \infty$$

and

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \int_0^t \int_{\mathbb{R}^2} G_{t-s}^2(x - y) \frac{\left(\mathbb{E}[|u(s, y) - u(s, z)|^p]\right)^{2/p}}{|y - z|^{2-2H}} dydzds < \infty.$$

The latter condition appears in a *natural* way, as we apply techniques from the theory of **fractional Sobolev spaces**.

# Strategy

In order to attain our objective, we have developed the following steps:

1. Properly *interpret* the **stochastic integral** with respect to our spatially homogeneous noise:

$$\int_0^t \int_{\mathbb{R}} S(s, y) X(ds, dy) \quad (\text{Basse-O'Connor } et al. 2012)$$

2. Obtain a new criterion for integrability, based on tools from the theory of **fractional Sobolev spaces** (Di Nezza *et al.* 2012).
3. Set a **Picard iteration scheme**, show that it is well-defined and converges, in a convenient topology, to a process which solves our SPDEs.

## Related results

Our main result covers the cases

$$\left\{ \begin{array}{l} \frac{\partial^2 u}{\partial t^2}(t, x) = \frac{\partial^2 u}{\partial x^2}(t, x) + u(t, x) \dot{X}(t, x), \quad x \in \mathbb{R} \\ u(0, x) = c, \quad \frac{\partial u}{\partial t}(0, x) = 0, \end{array} \right.$$

and

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t}(t, x) = \frac{1}{2} \frac{\partial^2 u}{\partial x^2}(t, x) + u(t, x) \dot{X}(t, x), \quad x \in \mathbb{R} \\ u(0, x) = c \end{array} \right.$$

- These are the **Hyperbolic Anderson Model** and **Parabolic Anderson Model**, resp.
- Study of the series of **multiple stochastic integrals** with respect to  $X$ .
- This method has been applied in
  - **Heat equations**: Hu 2001, Hu and Nualart 2009, Balan and Tudor 2010, Hu *et al.* 2011.
  - **Wave equations**: Dalang *et al.* 2008, Dalang and Mueller 2009, Balan 2012.

# Stochastic integral

**Wiener integral:** Let  $\mathcal{H}$  be the completion of  $\mathcal{D}(\mathbb{R}_+ \times \mathbb{R})$  with respect to

$$\langle \cdot, \cdot \rangle_{\mathcal{H}} := \mathbb{E}[X(\varphi)X(\psi)] = c_H \int_0^\infty \int_{\mathbb{R}} \mathcal{F}\varphi(t, \cdot)(\xi) \overline{\mathcal{F}\psi(t, \cdot)(\xi)} |\xi|^{1-2H} d\xi dt$$

Then,  $\varphi \mapsto X(\varphi) \in L^2(\Omega)$  is an **isometry** which can be extended to  $\mathcal{H}$ :

$$X(h) = \int_0^\infty \int_{\mathbb{R}} h(t, x) X(dt, dx), \quad h \in \mathcal{H}.$$

For  $t \geq 0$  any interval  $(x, y] \subset \mathbb{R}$ , one proves that  $\mathbf{1}_{(0,t] \times (x,y]} \in \mathcal{H}$ , so we can define the random variable

$$X_t((x, y]) := X(\mathbf{1}_{(0,t] \times (x,y]})$$

**Problem:** we cannot define  $X_t(A)$  for all  $A \in \mathcal{B}_b(\mathbb{R})$ , since in general the function  $\mathbf{1}_{(0,t] \times A}$  may not be in  $\mathcal{H}$  ( $H < 1/2$ ).

But recall that our noise  $X = \{X(\varphi), \varphi \in \mathcal{D}(\mathbb{R}_+ \times \mathbb{R})\}$  can be viewed as a **stationary random distribution** (Itô 1954, Yaglom 1957).

Hence,  $X$  admits a suitable **spectral representation** which can be applied to show that

$$X_t((x, y]) := X(1_{(0,t] \times (x,y]}) = \int_{\mathbb{R}} \mathcal{F}1_{(x,y]}(\xi) M_t(d\xi),$$

where  $\{M_t(A), \mathcal{F}_t, t \geq 0, A \in \mathcal{B}_b(\mathbb{R})\}$  is a (complex valued) **martingale measure** with zero mean and covariation

$$\langle M(A), M(B) \rangle_t = t \mu(A \cap B) = t c_H \int_{A \cap B} |\xi|^{1-2H} d\xi, \quad A, B \in \mathcal{B}_b(\mathbb{R}).$$

$(\mathcal{F}_t)_{t \geq 0}$  denotes the filtration generated by  $X$ :

$$\mathcal{F}_t = \sigma\{X(1_{[0,s]}\phi), s \in [0, t], \phi \in \mathcal{D}(\mathbb{R})\}$$



## Sketch of the construction of the stochastic integral:

1.  $\mathcal{E}$ : linear combinations of processes of the form  $g(\omega, t, x) = Y(\omega)1_{(a,b]}(t)1_{(c,d]}(x)$ . Define

$$\int_0^t \int_{\mathbb{R}} g(s, y) X(ds, dy) := Y(X_{t \wedge b}((u, v]) - X_{t \wedge a}((u, v]))$$

and extend to  $\mathcal{E}$  by linearity.

2. For any  $g \in \mathcal{E}$ , it holds

$$\int_0^t \int_{\mathbb{R}} g(s, y) X(ds, dy) = \int_0^t \int_{\mathbb{R}} \mathcal{F}g(s, \cdot)(\xi) M(ds, d\xi)$$

3. Let  $\mathcal{P}_0$  be the completion of  $\mathcal{E}$  with respect to

$$\|g\|_0^2 = \mathbb{E} \int_0^T \int_{\mathbb{R}} |\mathcal{F}g(t, \cdot)(\xi)|^2 c_H |\xi|^{1-2H} d\xi dt.$$

4. By the **isometry property** of Walsh's stochastic integral, the map  $\mathcal{E} \ni g \mapsto \{\int_0^t \int_{\mathbb{R}} g(s, y) X(ds, dy)\}_{t \in [0, T]} \in \mathcal{M}$  is an isometry, where  $\mathcal{M}$  is a subspace of the space of continuous square-integrable martingales with  $\|N\| = \{E(N_T^2)\}^{1/2}$ . This map can be extended to  $\mathcal{P}_0$ .

## Identification of integrands:

### Theorem (Basse-O'Connor *et al.* 2012)

The elements of  $\mathcal{P}_0$  are *predictable* functions of the form

$$S : \Omega \times [0, T] \rightarrow \mathcal{S}'(\mathbb{R})$$

such that  $\mathcal{F}S(\omega, t, \cdot)$  is a *locally integrable* function for any  $(\omega, t)$  and

$$\mathbb{E} \int_0^T \int_{\mathbb{R}} |\mathcal{F}S(t, \cdot)(\xi)|^2 c_H |\xi|^{1-2H} d\xi dt < \infty.$$

In particular, we have the *isometry*

$$\mathbb{E} \left| \int_0^t \int_{\mathbb{R}} S(s, x) X(ds, dx) \right|^2 = \mathbb{E} \int_0^t \int_{\mathbb{R}} |\mathcal{F}S(s, \cdot)(\xi)|^2 c_H |\xi|^{1-2H} d\xi ds,$$

**Remark:** all that we have done is valid for any  $H \in (0, 1)$ .

### Criterion for integrability:

A measurable function  $g : \mathbb{R} \rightarrow \mathbb{R}$  is **tempered** if there exists a tempered distribution  $T_g \in \mathcal{S}'(\mathbb{R})$  such that  $T_g \varphi = \int_{\mathbb{R}} g(x) \varphi(x) dx$ , for all  $\varphi \in \mathcal{S}(\mathbb{R})$ .

### Theorem

Let  $S : \Omega \times [0, T] \times \mathbb{R} \rightarrow \mathbb{R}$  be a **predictable** function, such that

- (a) for almost all  $(\omega, t) \in \Omega \times [0, T]$ ,  $S(\omega, t, \cdot)$  is a **tempered** function,
- (b) the Fourier transform  $\mathcal{F}S(\omega, t, \cdot)$  in  $\mathcal{S}'(\mathbb{R})$  is a **locally integrable** function.

If

$$I(T) := C_H \mathbb{E} \int_0^T \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{|S(t, x) - S(t, y)|^2}{|x - y|^{2-2H}} dx dy dt < \infty,$$

then  $S \in \mathcal{P}_0$  and

$$\mathbb{E} \left| \int_0^T \int_{\mathbb{R}} S(s, x) X(ds, dx) \right|^2 = I(T).$$

The proof of the above criterion is based on the following result, related to the theory of fractional Sobolev spaces (Di Nezza *et al.* 2012):

## Proposition

*Let  $g : \mathbb{R} \rightarrow \mathbb{R}$  be a tempered function whose Fourier transform in  $S'(\mathbb{R})$  is a locally integrable function. For any  $0 < H < 1/2$ ,*

$$c_H \int_{\mathbb{R}} |\mathcal{F}g(\xi)|^2 |\xi|^{1-2H} d\xi = C_H \int_{\mathbb{R}^2} \frac{|g(x) - g(y)|^2}{|x - y|^{2H-2}} dx dy,$$

*when either one of the two integrals above is finite.*

## Picard iteration scheme

For any  $(t, x) \in [0, T] \times \mathbb{R}$ , set  $u^0(t, x) = w(t, x)$  and, for  $n \geq 0$ ,

$$u^{n+1}(t, x) = w(t, x) + \int_0^t \int_{\mathbb{R}} G_{t-s}(x-y) \sigma(u^n(s, y)) X(ds, dy)$$

### Theorem

Let  $p \geq 2$  and  $\sigma$  be *Lipschitz*. Then,  $u^n(t, x)$  is well-defined and

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \mathbb{E}[|u^n(t, x)|^p] < \infty,$$

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \int_0^t \int_{\mathbb{R}^2} G_{t-s}^2(x-y) \frac{\left(\mathbb{E}[|u^n(s, y) - u^n(s, z)|^p]\right)^{2/p}}{|y-z|^{2-2H}} dy dz ds < \infty$$

and, for any  $h \in \mathbb{R}$  with  $|h| < 1$ ,

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \mathbb{E}[|u^n(t, x+h) - u^n(t, x)|^2] \leq C_n |h|^{2H}$$

$$\sup_{(t,x) \in [0, T \wedge (T-h)] \times \mathbb{R}} \mathbb{E}[|u^n(t+h, x) - u^n(t, x)|^2] \leq C_n |h|^\beta,$$

where  $\beta = 2H$  for the wave equation, and  $\beta = H$  for the heat equation.

## Remarks on the proof

We start with  $n = 0$ . Recall that, for the **wave equation**,

$$\begin{aligned}w(t, x) &= \int_{\mathbb{R}} G_t(x - y) v_0(y) dy + \frac{\partial}{\partial t} \left( \int_{\mathbb{R}} G_t(x - y) u_0(y) dy \right) \\ &= \frac{1}{2} \int_{x-t}^{x+t} v_0(y) dy + \frac{1}{2} (u_0(x+t) + u_0(x-t)),\end{aligned}$$

$$G_t(x) = \frac{1}{2} 1_{\{|x| < t\}}$$

and, for the **heat equation**,

$$w(t, x) = \int_{\mathbb{R}} G_t(x - y) u_0(y) dy$$

$$G_t(x) = \frac{1}{(2\pi t)^{1/2}} \exp\left(-\frac{|x|^2}{2t}\right)$$

Using the explicit expression of  $G_t(x)$  and that  $u_0, v_0$  are **bounded** and  **$H$ -Hölder** continuous, one proves

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} |w(t, x)| < \infty \quad \sup_{(t,x) \in [0, T] \times \mathbb{R}} |w(t, x+h) - w(t, x)|^2 \leq C|h|^{2H}$$

$$\sup_{(t,x) \in [0, T \wedge (T-h)] \times \mathbb{R}} |w(t+h, x) - w(t, x)|^2 \leq C|h|^\beta$$

It remains to study the expression

$$\int_0^t \int_{\mathbb{R}^2} G_{t-s}^2(x-y) \frac{|w(s, y) - w(s, z)|^2}{|y-z|^{2-2H}} dydzds$$

$$= \int_0^t \int_{\mathbb{R}} G_{t-s}^2(x-y) \left( \int_{\mathbb{R}} \frac{|w(s, y+z) - w(s, y)|^2}{|z|^{2-2H}} dz \right) dyds$$

Decomposing the domain of the  $dz$  integral, the latter term is bounded by

$$\int_0^t \int_{\mathbb{R}} G_{t-s}^2(x-y) \left( \int_{|z| \leq 1} |z|^{4H-2} dz + \int_{|z| > 1} |z|^{2H-2} dz \right) dyds,$$

which is uniformly bounded thanks to condition  $H \in (\frac{1}{4}, \frac{1}{2})$ .

In order to show that  $u^{n+1}(t, x)$  is **well-defined**, one needs to prove that the following **stochastic integral** is well-defined:

$$\int_0^t \int_{\mathbb{R}} G_{t-s}(x-y) \sigma(u^n(s, y)) X(ds, dy)$$

Hence, setting

$$S_n(s, y) := G_{t-s}(x-y) \sigma(u^n(s, y)) 1_{[0, t]}(s),$$

one proves

- (i)  $u^n$  has a predictable modification,
- (ii)  $S_n(\omega, s, \cdot) \in L^1(\mathbb{R})$  for almost all  $(\omega, s) \in \Omega \times [0, T]$ ,
- (iii)  $S_n$  satisfies

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \mathbb{E} \int_0^t \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{|S_n(s, y) - S_n(s, z)|^2}{|y - z|^{2H-2}} dy dz ds < \infty.$$



These conditions, together with all remaining estimates for  $u^{n+1}$  in the **induction hypothesis**, can be proved using the following type of techniques:

- $\sigma$  Lipschitz, Burkholder-Davis-Gundy inequality, Jensen inequality, Minkowski inequality (integrals), Fubini theorem, Plancherel theorem, and many changes of variables.
- For all  $\alpha \in (-1, 1)$ ,

$$\int_0^T \int_{\mathbb{R}} |\mathcal{F}G_t(\xi)|^2 |\xi|^\alpha d\xi dt = \begin{cases} C_1 T^{2-\alpha} & \text{wave} \\ C_2 T^{(1-\alpha)/2} & \text{heat} \end{cases}$$

- For any  $\alpha \in (-1, 1)$  and  $h \in \mathbb{R}$ ,

$$\int_0^T \int_{\mathbb{R}} |\mathcal{F}G_{t+h}(y) - \mathcal{F}G_t(y)|^2 |\xi|^\alpha d\xi dt \leq \begin{cases} CT|h|^{1-\alpha} & \text{wave} \\ C|h|^{(1-\alpha)/2} & \text{heat} \end{cases}$$

- For any  $\alpha \in (-1, 1)$  and  $h \in \mathbb{R}$ ,

$$\int_0^T \int_{\mathbb{R}} (1 - \cos(\xi h)) |\mathcal{F}G_t(\xi)|^2 |\xi|^\alpha d\xi dt \leq \begin{cases} CT|h|^{1-\alpha} & \text{wave} \\ C|h|^{1-\alpha} & \text{heat,} \end{cases}$$

In fact, in order to show that

$$\sup_{(t,x) \in [0, T] \times \mathbb{R}} \int_0^t \int_{\mathbb{R}^2} G_{t-s}^2(x-y) \frac{\left( \mathbb{E}[|u^{n+1}(s,y) - u^{n+1}(s,z)|^p] \right)^{2/p}}{|y-z|^{2-2H}} dydzds < \infty,$$

we are forced to estimate the term

$$\begin{aligned} & \int_0^t \int_{\mathbb{R}} \int_{\mathbb{R}} \frac{G_{t-s}^2(x-y)}{|z|^{2-2H}} \left( \int_0^s \int_{\mathbb{R}} |1 - e^{-i\xi z}|^2 |\mathcal{F}G_{s-r}(\xi)|^2 |\xi|^{1-2H} d\xi dr \right) dzdyds \\ & \leq \left( \int_0^t \int_{\mathbb{R}} G_{t-s}^2(x-y) dyds \right) \left( \int_0^T \int_{\mathbb{R}} |\mathcal{F}G_{s-r}(\xi)|^2 |\xi|^{2(1-2H)} d\xi dr \right). \end{aligned}$$

The latter integral is finite if and only if

$$-1 < 2(1 - 2H) < 1 \quad \iff \quad \frac{1}{4} < H < \frac{3}{4}$$

## Convergence of Picard iterations

Now we aim to prove that the sequence  $\{u^n(t, x), n \geq 0\}$  converges in  $L^p(\Omega)$ .

Here we assume that

$$|\sigma(x) - \sigma(y) - \sigma(u) + \sigma(v)| \leq C|x - y - u + v| \iff \sigma \text{ affine}$$

In fact, we prove convergence in the Banach space  $(\mathcal{X}, \|\cdot\|_{\mathcal{X}})$ : space of  $L^2(\Omega)$ -continuous and adapted processes  $Y = \{Y(t, x), (t, x) \in [0, T] \times \mathbb{R}\}$  such that  $\|Y\|_{\mathcal{X}_1} < \infty$  and  $\|Y\|_{\mathcal{X}_2} < \infty$ , where

$$\|Y\|_{\mathcal{X}_1} = \sup_{(t,x) \in [0,T] \times \mathbb{R}} \left( \mathbb{E}[|Y(t, x)|^p] \right)^{1/p}$$

and

$$\|Y\|_{\mathcal{X}_2} = \sup_{(t,x) \in [0,T] \times \mathbb{R}} \left( \int_0^t \int_{\mathbb{R}^2} G_{t-s}^2(x-y) \frac{\left( \mathbb{E}[|Y(s, y) - Y(s, z)|^p] \right)^{2/p}}{|y-z|^{2-2H}} dydzds \right)^{1/2}$$

For any  $Y \in \mathcal{X}$ , we define  $\|Y\|_{\mathcal{X}} := \|Y\|_{\mathcal{X}_1} + \|Y\|_{\mathcal{X}_2}$ .

## Theorem

The sequence  $(u^n)_{n \geq 0}$  converges in  $\mathcal{X}$  to a process  $u$ , which is  $L^2(\Omega)$ -continuous, and is the unique solution to equation (SWE) (or (SHE)).

**Proof:** We have

$$M_{n+1}(t) \leq \int_0^t (M_n(s) + M_{n-1}(s)) J(t-s) ds$$

where, setting  $m_n := u^n - u^{n-1}$ ,

$$\begin{aligned} M_n(t) &= \sup_{x \in \mathbb{R}} \left( \mathbb{E}[|m_n(t, x)|^p] \right)^{2/p} \\ &+ \sup_{x \in \mathbb{R}} \int_0^t \int_{\mathbb{R}^2} G_{t-s}^2(x-y) \frac{\left( \mathbb{E}[|m_n(s, y) - m_n(s, z)|^p] \right)^{2/p}}{|y-z|^{2-2H}} dy dz ds, \end{aligned}$$

$$J(t-s) = \int_{\mathbb{R}} |\mathcal{F}G_{t-s}(\xi)|^2 |\xi|^{1-2H} d\xi + \int_s^t \int_{\mathbb{R}} G_{t-r}^2(z) \int_{\mathbb{R}} |\mathcal{F}G_{r-s}(\xi)|^2 |\xi|^{2(1-2H)} d\xi dz dr$$

In fact, we have showed that

$$\int_s^t \int_{\mathbb{R}} G_{t-r}^2(z) \int_{\mathbb{R}} |\mathcal{F}G_{r-s}(\xi)|^2 |\xi|^{2(1-2H)} d\xi dz dr = \begin{cases} C_1 (t-s)^{4H-1} & \text{wave} \\ C_2 (t-s)^{2H-1} & \text{heat} \end{cases}$$

We have proved a version of Dalang's **Gronwall lemma** in order to treat situations of the form

$$f_n(t) \leq \int_0^t (f_{n-1}(s) + f_{n-2}(s))g(t-s) ds$$







Once we know that there exists  $u = \lim_n u^n$  in  $\mathcal{X}$ , we take limits in

$$u^{n+1}(t, x) = w(t, x) + \int_0^t \int_{\mathbb{R}} G_{t-s}(x-y) \sigma(u^n(s, y)) X(ds, dy)$$

to deduce that  $u = \{u(t, x), (t, x) \in [0, T] \times \mathbb{R}\}$  solves (SWE) (resp. (SHE)).

**Uniqueness** has been proved using similar arguments.

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