# Multiple points of the Brownian sheet in critical dimensions 

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## Overview

- Introduction to the Brownian sheet
- Hitting points, multiple points
- Intersection equivalence
- Main result: absence of multiple points in critical dimensions
- Method of proof


## The Brownian sheet

Fix two positive integers $d$ and $N$.
An $N$-parameter Brownian sheet with values in $\mathbb{R}^{d}$ is a Gaussian random field $B=\left(B^{1}, \ldots, B^{d}\right)$, defined on a probability space $(\Omega, \mathcal{F}, P)$, with parameter set $\mathbb{R}_{+}^{N}$, continuous sample paths and covariances

$$
\operatorname{Cov}\left(B^{i}(\mathbf{s}), B^{j}(\mathbf{t})\right)=\delta_{i, j} \prod_{\ell=1}^{N}\left(s_{\ell} \wedge t_{\ell}\right)
$$

where $\delta_{i, j}=1$ if $i=j$ and $\delta_{i, j}=0$ otherwise, $\mathbf{s}, \mathbf{t} \in \mathbb{R}_{+}^{N}, \mathbf{s}=\left(s_{1}, \ldots, s_{N}\right)$ and $\mathbf{t}=\left(t_{1}, \ldots, t_{N}\right)$.
The case $N=1$ : Brownian motion $B=\left(B(t), t \in \mathbb{R}_{+}\right)$.
The case $N>1$ : multi-parameter extension of Brownian motion.
A few references: Orey \& Pruitt (1973), R. Adler (1978), W. Kendall (1980), J.B. Walsh (1986), D. \& Walsh (1992), Khoshnevisan \& Shi (1999)
D. Khoshnevisan, Multiparameter processes, Springer (2002).


## Hitting probabilities

Basic questions, $N=1$.
(1) Hitting points. For which $d$ is $P\left\{\exists t \in \mathbb{R}_{+}^{*}: B(t)=x\right\}>0\left(x \in \mathbb{R}^{d}\right)$ ?
(2) Polar sets. For $I \subset \mathbb{R}_{+}$, let $B(I)=\{B(t): t \in I\}$ be the range of $B$ over $I$. Which sets $A \subset \mathbb{R}^{d}$ are polar $(P\{B(I) \cap A \neq \emptyset\}=0)$ ?
(3) Hitting probabilities. For $A \subset \mathbb{R}^{d}$, what are bounds on

$$
P\{B(I) \cap A \neq \emptyset\} ?
$$

(4) What is the Hausdorff dimension of the range of $B$ ? $\operatorname{dim} B\left(\mathbb{R}_{+}\right)=2 \wedge d$ a.s.
(5) What is the Hausdorff dimension of level sets of $B$ ?

$$
L(x)=\left\{t \in \mathbb{R}_{+}: B(t)=x\right\}
$$

If $d=1$, then $\operatorname{dim} L(x)=\frac{1}{2}$ a.s.

## Intersections of Brownian motions

Given $k \geqslant 2$ independent Brownian motions $B^{1}, \ldots, B^{k}$ with values in $\mathbb{R}^{d}$, what is the probability that their sample paths have a non-empty intersection? Is

$$
P_{\left(y_{1}, \ldots, y_{k}\right)}\left\{\exists\left(t_{1}, \ldots, t_{k}\right) \in\left(\mathbb{R}_{+}\right)^{k}: B^{1}\left(t_{1}\right)=\cdots=B^{k}\left(t_{k}\right)\right\}>0 ?
$$

( $y_{\ell}$ distinct) Equivalently, is

$$
P_{\left(y_{1}, \ldots, y_{k}\right)}\left\{B^{1}\left(\mathbb{R}_{+}\right) \cap \cdots \cap B^{k}\left(\mathbb{R}_{+}\right) \neq \emptyset\right\}>0 ?
$$

$d \geqslant 5$ : 2 independent BM's do not intersect (Kakutani 1944).
$d \geqslant 4$ : 2 independent BM's do not intersect.
$d=3$ : $P_{\left(x_{1}, x_{2}\right)}\left\{B^{1}\left(\mathbb{R}_{+}\right) \cap B^{2}\left(\mathbb{R}_{+}\right) \neq \emptyset\right\}>0$ (Dvoretzky, Erdős \& Kakutani 1950), but 3 independent BM's do not intersect (\& Taylor 1957).
$d=2$ : For all $k \geqslant 2$, sample paths of $k$ independent BM's intersect (D-E-K 1954).

## Self-intersections, multiple points

$x \in \mathbb{R}^{d}$ is a $k$-multiple point of $B$ if there exist distinct $t_{1}, \ldots, t_{k} \in \mathbb{R}_{+}$such that

$$
B\left(t_{1}\right)=\cdots=B\left(t_{k}\right)=x .
$$

We let $M_{k}$ denote the (random, possibly empty) set of all $k$-multiple points of $B$.

Existence of multiple points. Given a positive integer $k$, is

$$
P\left\{M_{k} \neq \emptyset\right\}>0 ?
$$

Existence of multiple points within a given set. Given a positive integer $k$ and a subset $A \subset \mathbb{R}^{d}$, is

$$
P\left\{M_{k} \cap A \neq \emptyset\right\}>0 ?
$$

## Relationship between self-intersections and intersections of independent motions

Case of Brownian motion (or of Markov processes).
Given a Brownian motion $B$, a double point (or 2-multiple point) occurs if there are two disjoint intervals $I_{1}$ and $I_{2}$ in $\mathbb{R}_{+}$such that

$$
\begin{equation*}
B\left(I_{1}\right) \cap B\left(I_{2}\right) \neq \emptyset \tag{1}
\end{equation*}
$$

Suppose $I_{1}$ precedes $I_{2}$. By the Markov property of $B$, given the position of $B$ at the right endpoint of $I_{1},\left.B\right|_{I_{2}}$ is conditionally independent of $\left.B\right|_{1_{1}}$, so the study of (1) is essentially the study of intersections of two independent Brownian motions.

For random fields, this type of Markov property is absent, so other methods are needed.

## Case $N>1$ : the Brownian sheet

(1) (Orey \& Pruitt, 1973). Points are polar for the $(N, d)$-Brownian sheet if and only if $d \geqslant 2 N$.
(2) (J. Rosen, 1984) If $d(k-1)<2 k N$, then the Hausdorff dimension of the set of $k$-multiple points is $k N-d(k-1) / 2$.
(3) (Khoshnevisan, 1997). The ( $N, d$ )-Brownian sheet does not have $k$-multiple points if $d(k-1)>2 k N$.
Remark. The critical case $d(k-1)=2 k N$ remained open.
(4) Double points (D. et al, Annals Probab. 2012). In the case $k=2$ and for critical dimensions $d=4 N$, the $(N, d)$-Brownian sheet does not have double points.

## Theorem 1 (D. \& Mueller, today's talk)

Absence of $k$-multiple points, $k \geqslant 2$ : If $N, d$ and $k$ are such that $(k-1) d=2 k N$, then an $(N, d)$-Brownian sheet has no $k$-multiple points.

## Non-critical dimensions

Case $N=1, d \geqslant 3$ : standard Brownian motion with values in $\mathbb{R}^{d}$ does not hit points.
Explanation. Let $t_{k}=1+k 2^{-2 n}$. Fix $x \in \mathbb{R}^{d}$. Then

$$
\begin{aligned}
P\{\exists t \in[1,2]: B(t)=x\} & =P\left(\bigcup_{k=1}^{2^{2 n}}\left\{\exists t \in\left[t_{k-1}, t_{k}\right]: B(t)=x\right\}\right) \\
& \leqslant \sum_{k=1}^{2^{2 n}} P\left\{\exists t \in\left[t_{k-1}, t_{k}\right]: B(t)=x\right\} \\
& \sim \sum_{k=1}^{2^{2 n}} P\left\{\left\|B_{t_{k}}-x\right\| \leqslant n 2^{-n}\right\} \\
& \leqslant \sum_{k=1}^{2^{2 n}} c\left(n 2^{-n}\right)^{d} \\
& =c 2^{2 n} c\left(n 2^{-n}\right)^{d} \\
& =c n^{d} 2^{(2-d) n} \\
& \rightarrow 0 \text { as } n \rightarrow+\infty \text { (because } d \geqslant 3 \text { ). }
\end{aligned}
$$

## Anisotropic Gaussian fields, generic results (Xiao, 2008)

Let $\left(V(x), x \in \mathbb{R}^{k}\right)$ be a centered continuous Gaussian random field with values in $\mathbb{R}^{d}$ with i.i.d. components: $V(x)=\left(V_{1}(x), \ldots, V_{d}(x)\right)$. Set

$$
\sigma^{2}(x, y)=E\left[\left(V_{1}(x)-V_{1}(y)\right)^{2}\right] .
$$

Let I be a "rectangle". Assume the two conditions:
(C1) There exists $0<c<\infty$ and $\left.H_{1}, \ldots, H_{k} \in\right] 0,1[$ such that for all $x \in I$,

$$
c^{-1} \leqslant \sigma^{2}(0, x) \leqslant c
$$

and for all $x, y \in I$,

$$
c^{-1} \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{2 H_{j}} \leqslant \sigma^{2}(x, y) \leqslant c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{2 H_{j}}
$$

( $H_{j}$ is the Hölder exponent for coordinate $j$ ).
(C2) There is $c>0$ such that for all $x, y \in I$,

$$
\operatorname{Var}\left(V_{1}(y) \mid V_{1}(x)\right) \geqslant c \sum_{j=1}^{k}\left|x_{j}-y_{j}\right|^{2 H_{j}}
$$

## Anisotropic Gaussian fields

Theorem 1 (Biermé, Lacaux \& Xiao, 2007)
Fix $M>0$. Set

$$
Q=\sum_{j=1}^{k} \frac{1}{H_{j}} .
$$

Assume $d>Q$. Then there is $0<C<\infty$ such that for every compact set $A \subset B(0, M)$,

$$
C^{-1} C a p_{d-Q}(A) \leqslant P\{V(I) \cap A \neq \emptyset\} \leqslant C \mathcal{H}_{d-Q}(A) .
$$

Special case obtained by D., Khoshnevisan and E. Nualart (2007); see also D. \& Sanz-Solé (2010).

This results tells us what sort of inequality to aim for when we have information about Hölder exponents.

Notice the Hausdorff measure appearing on the right-hand side.

## Measuring the size of sets: capacity

Capacity. $\mathrm{Cap}_{\beta}(A)$ denotes the Bessel-Riesz capacity of $A$ :

$$
\begin{gathered}
\operatorname{Cap}_{\beta}(A)=\frac{1}{\inf _{\mu \in \mathcal{P}(A)} \mathcal{E}_{\beta}(\mu)}, \\
\mathcal{E}_{\beta}(\mu)=\int_{\mathbb{R}^{d}} \int_{\mathbb{R}^{d}} k_{\beta}(x-y) \mu(d x) \mu(d y)
\end{gathered}
$$

and

$$
k_{\beta}(x)= \begin{cases}\|x\|^{-\beta} & \text { if } 0<\beta<d \\ \ln \left(\frac{1}{\|x\|}\right) & \text { if } \beta=0 \\ 1 & \text { if } \beta<0\end{cases}
$$

Examples. If $A=\{z\}$, then:

$$
\operatorname{Cap}_{\beta}(\{z\})= \begin{cases}1 & \text { if } \beta<0 \\ 0 & \text { if } \beta \geqslant 0\end{cases}
$$

If $A$ is a subspace of $\mathbb{R}^{d}$ with dimension $\ell \in\{1, \ldots, d-1\}$, then:

$$
\operatorname{Cap}_{\beta}(A) \begin{cases}>0 & \text { if } \beta<\ell \\ =0 & \text { if } \beta \geqslant \ell\end{cases}
$$

## Another measure of the size of sets: Hausdorff measure

For $\beta \geqslant 0$, the $\beta$-dimensional Hausdorff measure of $A$ is defined by

$$
\mathcal{H}_{\beta}(A)=\lim _{\epsilon \rightarrow 0^{+}} \inf \left\{\sum_{i=1}^{\infty}\left(2 r_{i}\right)^{\beta}: A \subseteq \bigcup_{i=1}^{\infty} B\left(x_{i}, r_{i}\right), \sup _{i \geq 1} r_{i} \leqslant \epsilon\right\}
$$

When $\beta<0$, we define $\mathcal{H}_{\beta}(A)$ to be infinite.
Note. For $\beta_{1}>\beta_{2}>0$,

$$
\operatorname{Cap}_{\beta_{1}}(A)>0 \Rightarrow \mathcal{H}_{\beta_{1}}(A)>0 \Rightarrow \operatorname{Cap}_{\beta_{2}}(A)>0
$$

Example. $A=\{z\}$

$$
\mathcal{H}_{\beta}(\{z\})= \begin{cases}\infty & \text { if } \beta<0 \\ 1 & \text { if } \beta=0 \\ 0 & \text { if } \beta>0\end{cases}
$$

Remark. For $\beta=0$,

$$
\operatorname{Cap}_{0}(\{z\})=0<\mathcal{H}_{0}(\{z\})=1
$$

## Situation in the critical dimension $d=Q$

When $d=Q$ and $A=\{x\}$, the inequality

$$
C^{-1} \operatorname{Cap}_{d-Q}(A) \leqslant P\{V(I) \cap A \neq \emptyset\} \leqslant C \mathcal{H}_{d-Q}(A)
$$

is equivalent to

$$
0 \leqslant P\{x \text { is polar }\} \leqslant 1
$$

which is uninformative!

## Reducing "multiple points" to "hitting points"

Let

$$
X\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right)=\left(B\left(\mathbf{t}^{1}\right)-B\left(\mathbf{t}^{2}\right), B\left(\mathbf{t}^{2}\right)-B\left(\mathbf{t}^{3}\right), \ldots, B\left(\mathbf{t}^{k-1}\right)-B\left(\mathbf{t}^{k}\right)\right)
$$

Then

$$
B\left(\mathbf{t}^{1}\right)=\cdots=B\left(\mathbf{t}^{k}\right) \Longleftrightarrow X\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right)=0 \in\left(\mathbb{R}^{d}\right)^{k-1}
$$

Existence of $k$-multiple points for $B$ is equivalent to hitting 0 for $X$.
Remark. The probability density function of $X\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right)$ is related to the joint probability density function of $\left(B\left(\mathbf{t}^{1}\right), \ldots, B\left(\mathbf{t}^{k}\right)\right)$, so the difficulty lies in getting properties of the joint density.

## Intersection-equivalence

Let $\mathcal{T}_{N}^{k}$ denote the set of parameters $\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right)$ with $\left.\mathbf{t}^{i} \in\right] 0, \infty\left[{ }^{N}\right.$ such that no two $\mathbf{t}^{i}=\left(t_{1}^{i}, \ldots, t_{N}^{i}\right)$ and $\mathbf{t}^{j}=\left(t_{1}^{j}, \ldots, t_{N}^{j}\right)(i \neq j)$ share a common coordinate:

$$
\begin{array}{r}
\mathcal{T}_{N}^{k}=\left\{\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right) \in(] 0, \infty\left[^{N}\right)^{k}: t_{\ell}^{i} \neq t_{\ell}^{j}, \text { for all } 1 \leq i<j \leq k\right. \\
\text { and } \ell=1, \ldots, N\} .
\end{array}
$$

## Theorem 2

Let $A \subset \mathbb{R}^{d}$ be a Borel set. For all $k \in\{2,3, \ldots\}$, we have

$$
P\left\{\exists\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right) \in \mathcal{T}_{N}^{k}: B\left(\mathbf{t}^{1}\right)=\cdots=B\left(\mathbf{t}^{k}\right) \in A\right\}>0
$$

if and only if

$$
P\left\{\exists\left(\mathbf{t}^{1}, \ldots, \mathbf{t}^{k}\right) \in \mathcal{T}_{N}^{k}: W_{1}\left(\mathbf{t}^{1}\right)=\cdots=W_{k}\left(\mathbf{t}^{k}\right) \in A\right\}>0
$$

where $W_{1}, \ldots, W_{k}$ are independent $N$-parameter Brownian sheets with values in $\mathbb{R}^{d}$.

## Using Theorem 1

## Theorem 3 (Khoshnevisan and Shi, 1999)

Fix $M>0$ and $0<a_{\ell}<b_{\ell}<\infty(\ell=1, \ldots, N)$. Let

$$
I=\left[a_{1}, b_{1}\right] \times \cdots \times\left[a_{N}, b_{N}\right] .
$$

There exists $0<C<\infty$ such that for all compact sets $A \subset B(0, M)$,

$$
\begin{equation*}
\frac{1}{C} \operatorname{Cap}_{d-2 N}(A) \leqslant P\{B(I) \cap A \neq \emptyset\} \leqslant C \operatorname{Cap}_{d-2 N}(A) . \tag{2}
\end{equation*}
$$

(Cap denotes Bessel-Riesz capacity)

## Theorem 4 (Peres, 1999)

Property (2) implies that if $W_{1}, \ldots, W_{k}$ are independent $N$-parameter Brownian sheets with values in $\mathbb{R}^{d}$ and $d>2 N$, then

$$
\frac{1}{C} \operatorname{Cap}_{k(d-2 N)}(A) \leqslant P\left\{W_{1}\left(I_{1}\right) \cap \cdots \cap W_{k}\left(I_{k}\right) \cap A \neq \emptyset\right\} \leqslant C \operatorname{Cap}_{k(d-2 N)}(A)
$$

In particular, the r.h.s. is 0 if $A=\mathbb{R}^{d}$ and $k(d-2 N)=d$, i.e. $(k-1) d=2 k N$.

## Creating independence while preserving absolute continuity

## Theorem 5

Let $B$ be a Brownian sheet and let $W_{1}, \ldots, W_{k}$ be independent Brownian sheets. Fix $M>0$ and $k$ boxes $R_{1}, \ldots, R_{k}$, where, for each coordinate axis, the projections of the $R_{i}$ onto this coordinate axis are pairwise disjoint. Then, for all $\left(R_{1}, \ldots, R_{k}\right) \in \mathcal{R}_{M}$, the random vectors

$$
\left(\left.B\right|_{R_{1}}, \ldots,\left.B\right|_{R_{k}}\right) \quad \text { and } \quad\left(\left.W_{1}\right|_{R_{1}}, \ldots,\left.W_{k}\right|_{R_{k}}\right)
$$

(with values in $\left(C\left(R_{1}, \mathbb{R}^{d}\right) \times \cdots \times C\left(R_{k}, \mathbb{R}^{d}\right)\right)$ ) have mutually absolutely continuous probability distributions.

## Comments.

(1) There is no convenient Markov property to use.
(2) If the projections of the boxes are not disjoint, then this property would fail.
(3) D. et al 2012: used quantitative estimates on the conditional distribution of $\left.B\right|_{R_{k}}$ given $\left(\left.B\right|_{R_{1}}, \ldots,\left.B\right|_{R_{k-1}}\right)$. This was only achieved for certain configurations of boxes, which limited the final result to double points (2 boxes).

## First main ingredient in the proof of Theorem 5

Fix $M>0$. Define the one-parameter filtration $\mathcal{G}=\left(\mathcal{G}_{u}, u \in[0, M]\right)$ by

$$
\mathcal{G}_{u}=\sigma\left\{B\left(t_{1}, \ldots, t_{N-1}, v\right):\left(t_{1}, \ldots, t_{N-1}\right) \in \mathbb{R}_{+}^{N-1}, v \in[0, u]\right\}
$$

Let $\left(Z(\mathbf{s})\right.$, $\left.\mathbf{s} \in \mathbb{R}_{+}^{N-1} \times[0, M]\right)$ be an $\mathbb{R}^{d}$-valued adapted random field: for all $\mathbf{s} \in \mathbb{R}_{+}^{N-1} \times[0, M], Z(\mathbf{s})$ is $\mathcal{G}_{s_{N}}$-measurable. For $u \in[0, M]$, define

$$
L_{u}=\exp \left(\int_{\mathbb{R}_{+}^{N-1} \times[0, u]} Z(\mathbf{s}) \cdot d B(\mathbf{s})-\frac{1}{2} \int_{\mathbb{R}_{+}^{N-1} \times[0, u]}\|Z(\mathbf{s})\|^{2} d \mathbf{s}\right)
$$

## Theorem 6 (Cameron-Martin-Girsanov)

If $\left(L_{u}, u \in[0, M]\right)$ is a martingale with respect to $\mathcal{G}$, then the process $\left(\tilde{B}(\mathbf{t}), \mathbf{t} \in \mathbb{R}_{+}^{N-1} \times[0, M]\right)$ defined by

$$
\tilde{B}\left(t_{1}, \ldots, t_{N}\right)=B\left(t_{1}, \ldots, t_{N}\right)-\int_{\left[0, t_{1}\right] \times \cdots \times\left[0, t_{N}\right]} Z\left(s_{1}, \ldots, s_{N}\right) d s_{1} \cdots d s_{N}
$$

is an $\mathbb{R}^{d}$-valued Brownian sheet under the probability measure $Q$, where $Q$ is defined by

$$
\frac{d Q}{d P}=L_{M}
$$

## Using Girsanov to create independence

Case $N=1$. Let $\left(B_{t}, t \in \mathbb{R}_{+}\right)$be a Brownian motion. Show that

$$
\operatorname{Law}\left(\left(B_{t}, t \in[1,2]\right),\left(B_{t}, t \in[3,4]\right),\left(B_{t}, t \in[5,6]\right)\right)
$$

is mutually absolutely continuous w.r.t.

$$
\operatorname{Law}\left(\left(W_{t}^{(1)}, t \in[1,2]\right),\left(W_{t}^{(2)}, t \in[3,4]\right),\left(W_{t}^{(3)}, t \in[5,6]\right)\right)
$$

where $\left(W_{t}^{(j)}\right)$ are independent Brownian motions.
By Girsanov's theorem: $\left(B_{t}, t \in[0,6]\right) \sim\left(\tilde{B}_{t}=B_{t}-\int_{0}^{t} h_{s} d s, t \in[0,6]\right)$.
Define $\left(h_{s}, s \in[0,6]\right)$ by


$$
\tilde{B}_{t}= \begin{cases}B_{t}, & t \in I_{1} \\ B_{t}-B_{2}, & t \in I_{2} \\ B_{t}-B_{4}, & t \in I_{3}\end{cases}
$$

Set $W_{t}^{(j)}=\tilde{B}_{t}, t \in I_{i}$. Then the $\left(W_{t}^{(j)}, t \in I_{j}\right)$ are independent.
Observation. For $t \in I_{3}, \quad \tilde{B}_{t}=B_{t}-E\left(B_{t} \mid \mathcal{F}\left(l_{1}\right) \vee \mathcal{F}\left(l_{2}\right)\right)$.

$$
\text { For } t \in I_{2}, \quad \tilde{B}_{t}=B_{t}-E\left(B_{t} \mid \mathcal{F}\left(I_{1}\right)\right) \text {. }
$$

## Obtain conditional expectations via a Girsanov transformation

Case $N=2$.
Fix $k \geqslant 2$ and consider $k$ boxes $R_{1}, \ldots, R_{k}$ with disjoint projections on each coordinate axis:

$$
R_{j}=\iota_{j}^{1} \times \iota_{j}^{2}, \quad j=1, \ldots, k
$$

where, for $\ell=1,2$, the intervals $l_{1}^{\ell}, \ldots, l_{k}^{\ell}$ are pairwise disjoint. We assume that

$$
I_{1}^{2}<I_{2}^{2}<\cdots<I_{k}^{2} .
$$

Let

$$
S=\left(I_{k}^{1}\right)^{c} \times\left[0, \sup I_{k-1}^{2}\right] .
$$

Notice that for $j=1, \ldots, k-1, R_{j} \subset S$, and there is some space between $S$ and $R_{k}$.

## Illustration



Then for $\mathbf{t} \in R_{k}, E(B(\mathbf{t}) \mid \mathcal{F}(S))=\tilde{B}(\mathbf{t})$, where

$$
\tilde{B}\left(t^{1}, t^{2}\right)=\frac{t^{1}-u_{k}^{1}}{v_{k}^{1}-u_{k}^{1}} B\left(v_{k}^{1}, v_{k-1}^{2}\right)+\frac{v_{k}^{1}-t^{1}}{v_{k}^{1}-u_{k}^{1}} B\left(u_{k}^{1}, v_{k-1}^{2}\right) .
$$

## Creating independent while preserving absolute continuity

For $\left.s^{1} \in\right] 0, v_{k}^{1}\left[\right.$ and $\left.s^{2} \in\right] v_{k-1}^{2}, u_{k}^{2}[$, let

$$
Z\left(s^{1}, s^{2}\right)=\frac{\partial^{2}}{\partial s^{1} \partial s^{2}}\left(\frac{s^{2}-v_{k-1}^{2}}{u_{k}^{2}-v_{k-1}^{2}} \frac{s^{1} \wedge u_{k}^{1}}{u_{k}^{1}} \tilde{B}\left(s^{1} \vee u_{k}^{1}, v_{k-1}^{2}\right)\right),
$$

and $Z\left(s^{1}, s^{2}\right)=0$ otherwise.
Define

$$
\hat{B}(\mathbf{t})=B(\mathbf{t})-\int_{[0, \mathrm{t}]} Z\left(s^{1}, s^{2}\right) d s^{1} d s^{2} .
$$

Facts.
(a) For $\mathbf{t} \in R_{k}$,

$$
\hat{B}(\mathbf{t})=B(\mathbf{t})-E(B(\mathbf{t}) \mid \mathcal{F}(S)),
$$

and the r.h.s. is independent of $\mathcal{F}(S)$ (Gaussian process).
(b) $\hat{B}=B$ on $R_{1} \cup \cdots \cup R_{k-1}$.
(c) $\operatorname{Law}(\hat{B}) \sim \operatorname{Law}(B)$.

## Concluding the proof

We proceed by induction:

$$
\begin{aligned}
\operatorname{Law}\left(\left.B\right|_{R_{1}}, \ldots,\left.B\right|_{R_{k}}\right) & \sim \operatorname{Law}\left(\left.\hat{B}\right|_{R_{1}}, \ldots,\left.\hat{B}\right|_{R_{k-1}},\left.\hat{B}\right|_{R_{k}}\right) \\
& \sim \operatorname{Law}\left(\left.\hat{B}\right|_{R_{1}}, \ldots,\left.\hat{B}\right|_{R_{k-1}},\left.W_{k}\right|_{R_{k}}\right) \\
& \sim \operatorname{Law}\left(\left.B\right|_{R_{1}}, \ldots,\left.B\right|_{R_{k-1}},\left.W_{k}\right|_{R_{k}}\right)
\end{aligned}
$$

where $W_{k}$ and $B$ are independent. Then we use induction to replace the other terms:

$$
\sim \operatorname{Law}\left(\left.W_{1}\right|_{R_{1}}, \ldots,\left.W_{k-1}\right|_{R_{k-1}},\left.W_{k}\right|_{R_{k}}\right)
$$

where $W_{1}, \ldots, W_{k}$ are independent Brownian sheets.
Use the results of Khoshnevisan \& Shi and Peres to conclude.

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