Existence of densities for non smooth SDEs.

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▶ SDEs driven by Levy noise with irregular coefficients in \mathbb{R}^d :

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$
 (1)

with *b* and σ only Hölder (or even only bounded for *b*) \rightsquigarrow no Malliavin calculus.

If *b* and σ are smooth, Malliavin calculus can be developped (Bitcheler-Gravereaux-Jacod, 1987, Picard, 1996, ...)

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- ▶ application to process used in the probabilistic representation of the homogeneous Boltzmann equation: when d = 3, the collision Kernel is too singular.
- ► develop a method to prove existence of densities without Malliavin calculus → application to SPDEs for instance: the application we have in mind is the 3D Navier-Stokes equations where it is not known whether the solutions are Malliavin differentiable.

$$X_t = x + \int_0^t \sigma(X_s) dW_s + \int_0^t b(X_s) ds$$
 (2)

Now, W is a *d*-dimensional brownian motion.

1) Take $\epsilon > 0$ small and define

$$X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon})(W(t) - W(t-\epsilon)) + \epsilon b(X_{t-\epsilon})$$

- 2) If σ is non degenerate, X_t^{ϵ} has a smooth density
- Use the fact that X^e and X are close to obtain the existence of a density for X_t

$$X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon})(W(t) - W(t-\epsilon)) + \epsilon b(X_{t-\epsilon})$$

First possibility: Use Characteristic functions (Fournier and Printems)

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ight)
ight) \ &= \mathbb{E}\left(e^{i\langle X_{t-\epsilon}+\epsilon b(X_{t-\epsilon}),\xi
angle-rac{\epsilon}{2}|\sigma(X_{t-\epsilon})\xi|^{2}}
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If **b** is bounded, σ is γ Hölder and elliptic.

$$\mathbb{E}(e^{i\langle\xi,X_t}) \leq Ce^{-lpha\epsilon\xi^2} + \widetilde{C}|\xi|\epsilon^{rac{1+\gamma}{2}}$$

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$$\mathsf{Take}\; \epsilon = \tfrac{(\ln \xi)^2}{\xi^2} \rightsquigarrow \mathbb{E}(e^{i\langle \xi, X_t}) \leq C \tfrac{(\ln \xi)^{\gamma+1}}{|\xi|^{\gamma}}$$

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 \rightsquigarrow If $\gamma > 1/2$ and d = 1, the characteristic function is in $L^2(\mathbb{R})$ and by Plancherel, X_t has a density in $L^2(\mathbb{R})$.

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• If $\gamma > 1/2$, the method gives a little more: since $|\xi|^{\eta} \mathbb{E}(e^{i\langle \xi, X_t})$ is in $L^2(\mathbb{R})$, the density has some extra regularity.

We keep the first ingredient (approximation of X_t by X_t^{ϵ}) but instead of using the characteristic function, we go bak to the basic idea of Malliavin: use an integration by part. Since we do not expect to have very smooth density, we use discrete derivatives \rightsquigarrow try to estimate:

$$\mathbb{E}(\varphi(X_t+h)-\varphi(X_t)) = \int_{\mathbb{R}^d} (\varphi(x+h)-\varphi(x)) f_{X_t}(x) dx$$

=
$$\int_{\mathbb{R}^d} \varphi(x) (f_{X_t}(x-h)-f_{X_t}(x)) dx.$$

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If we are able to prove

$$|\mathbb{E}(arphi(X_t+h)-arphi(X_t))|\leq C\|arphi\|_{\infty}\|h\|^{\eta}.$$

This (formally) says that

$$\int_{\mathbb{R}^d} |f_{X_t}(x+h) - f_{X_t}(x)| dx \leq C \|h\|^{\eta}.$$

The Besov space $B_{1,\infty}^s$

The Besov space $B_{1,\infty}^s$ can be characterized in terms of finite differences: define

$$(\Delta_h^1 f)(x) = f(x+h) - f(x),$$

then, for s < 1,

$$\|f\|_{B^s_{1,\infty}} = \|f\|_{L^1} + \sup_{|h| \le 1} \frac{\|\Delta^1_h f\|_{L^1}}{|h|^s},$$

is an equivalent norm of $B_{1,\infty}^s(\mathbb{R}^d)$. Moreover $B_{1,\infty}^s(\mathbb{R}^d)$ can be defined as the set of $L^1(\mathbb{R}^d)$ functions such that these quantities are finite.

It is well know that we have $s > \tilde{s}$, $p \in [1, d/(d - \tilde{s})]$:

$$B^s_{1,\infty}(\mathbb{R}^d) \subset B^{\widetilde{s}}_{1,1}(\mathbb{R}^d) = W^{\widetilde{s},1}(\mathbb{R}^d) \subset L^p(\mathbb{R}^d).$$

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It is well know that we have $s > \tilde{s}$, $p \in [1, d/(d - \tilde{s})]$:

 $B_{1,\infty}^{s}(\mathbb{R}^{d}) \subset B_{1,1}^{\tilde{s}}(\mathbb{R}^{d}) = W^{\tilde{s},1}(\mathbb{R}^{d}) \subset L^{p}(\mathbb{R}^{d}).$ $\rightsquigarrow f_{X_{t}} \in B_{1,\infty}^{\eta}(\mathbb{R}^{d}) \text{ and thus in } L^{p}(\mathbb{R}^{d}) \text{ for some } p > 1.$

We again use X_t^{ϵ} and write:

$$\begin{split} \mathbb{E}(\varphi(X_t+h)-\varphi(X_t))| &\leq & |\mathbb{E}(\varphi(X_t^{\epsilon}+h)-\varphi^{\epsilon}(X_t^{\epsilon}))| \\ &+ |\mathbb{E}(\varphi(X_t+h)-\varphi(X_t^{\epsilon}+h)| \\ &+ |\mathbb{E}(\varphi(X_t)-\varphi(X_t^{\epsilon}))| \end{split}$$

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with $\epsilon = \|h\|^{\frac{2}{\eta(1+\gamma)+1}}$.

We thus obtain the weaker inequality:

 $\mathbb{E}(\varphi(X_t+h)-\varphi(X_t))| \leq C \|h\|^{\frac{\eta(1+\gamma)}{\eta(1+\gamma)+1}} \|\varphi\|_{C^{\eta}}$

Since $\frac{\eta(1+\gamma)}{\eta(1+\gamma)+1} > \eta$ for $\eta < \frac{\gamma}{1+\gamma}$, we have a gain in regularity.

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Since $\frac{\eta(1+\gamma)}{\eta(1+\gamma)+1} > \eta$ for $\eta < \frac{\gamma}{1+\gamma}$, we have a gain in regularity. Lemma Let $g \in \mathcal{M}(\mathbb{R}^d)$. Assume that there are $0 < \eta < a < 1$ and a constant K such that for all $\phi \in C^{\eta}(\mathbb{R}^d)$, all $h \in \mathbb{R}^d$ with $|h| \leq 1$,

$$\left|\int_{\mathbb{R}^d} \Delta_h^1 \phi(x) g(dx)\right| \le K ||\phi||_{C^\eta(\mathbb{R}^d)} |h|^a.$$
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Then, for any $\gamma \in (0, a - \eta)$, g has a density in $B_{1,\infty}^{\gamma}$.

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Then, for any $\gamma \in (0, a - \eta)$, g has a density in $B_{1,\infty}^{\gamma}$.

 \rightsquigarrow We obtain a density with Besov regularity under the assumption $\gamma > 0$.

Remarks

- The above argument can be slightly improved and a Besov regularity of order < γ can be obtained</p>
- Also, we do not need $\gamma > 1/2$.
- The obtained regularity is low and not optimal at all ! By PDE argument, much more regularity can be obtained.
- In the Brownian case, when σ is invertible, Girsanov formula can be used. However, this method can be applied in situations where Girsanov formula does not apply. For instance if X_t is the solution of a SPDE.

We consider, on some filtered probability space $(\Omega, \mathcal{F}, (\mathcal{F}_t)_{t \ge 0}, \mathbb{P})$, a pure jump *d*-dimensional Lévy process $(Z_t)_{t \ge 0}$ with Lévy measure *m*.

Denote by f_{Z_t} the law of Z_t and recall that for $\xi \in \mathbb{R}^d$

$$\begin{cases} \widehat{f_{Z_t}}(\xi) := \mathbb{E}[\exp(i\langle\xi, Z_t\rangle)] = \exp(-t\Psi(\xi)), \\ \text{where} \quad \Psi(\xi) = \int_{\mathbb{R}^d} \left(1 - e^{i\langle\xi, z\rangle} + i\langle\xi, z\rangle \, \mathrm{I}_{\{|z| \le 1\}}\right) m(dz). \end{cases}$$

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Let $(X_t)_{t\geq 0}$ be a $(\mathcal{F}_t)_{t\geq 0}$ -adapted càdlàg solution to

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

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We introduce $X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon})(Z_t - Z_{t-\epsilon}) + \epsilon b(X_{t-\epsilon})$ We need two ingredients:

- Prove that X^e_t has a smooth density and measure its smoothness in terms of e
- Estimate precisely how X_t and X_t^{ϵ} are close.

$$X_{t} = x + \int_{0}^{t} \sigma(X_{s-}) dZ_{s} + \int_{0}^{t} b(X_{s}) ds$$
$$X_{t}^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon}) (Z_{t} - Z_{t-\epsilon}) + \epsilon b(X_{t-\epsilon})$$

If σ is invertible, the smoothness of the density of X_t^{ϵ} is obtained thanks to the smoothness of $Z_t - Z_{t-\epsilon}$

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If σ is invertible, the smoothness of the density of X_t^{ϵ} is obtained thanks to the smoothness of $Z_t - Z_{t-\epsilon}$ We consider stable like processes:

 $\begin{cases} (\mathrm{i}) \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ (\mathrm{ii}) \exists C > 0, \ \forall \ a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^{2} m(dz) \le Ca^{2-\alpha}, \\ (\mathrm{iii}) \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^{d}} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{cases}$

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$$X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon}) (Z_t - Z_{t-\epsilon}) + \epsilon b(X_{t-\epsilon})$$

If σ is invertible, the smoothness of the density of X_t^{ϵ} is obtained thanks to the smoothness of $Z_t - Z_{t-\epsilon}$ We consider stable like processes:

 $\begin{cases} (i) \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ (ii) \exists C > 0, \ \forall \ a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^2 m(dz) \le Ca^{2-\alpha}, \\ (iii) \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^d} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{cases}$ $\rightsquigarrow c|\xi|^{\alpha} \leq \Re \ \Psi(\xi) \leq C|\xi|^{\alpha}, \ \hat{f}_{Z_t} \text{ decays very fast and } f_{Z_t} \text{ is smooth.}$ Schilling, Sztonyk, Wang have proved that this implies that $\|\partial^{\beta} f_{Z_{t}}\|_{L^{1}(\mathbb{R}^{d})} \leq C(m)t^{-m/\alpha}$ for $|\beta| = m$.

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

$$X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon}) (Z_t - Z_{t-\epsilon}) + \epsilon b(X_{t-\epsilon})$$

We deduce that X_t^{ϵ} has a density $f_{X_t^{\epsilon}}$ such that

 $\|f_{X_t^{\epsilon}}\|_{B_{\infty,1}^m(\mathbb{R}^d)} \leq C(\delta)\|f_{X_t^{\epsilon}}\|_{B_{1,1}^m(\mathbb{R}^d)} = \|f_{X_t^{\epsilon}}\|_{W^{m,1}(\mathbb{R}^d)} \leq C(m,\delta)\epsilon^{-m/\alpha}.$

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

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The Besov space $B_{1,\infty}^s$ can also be characterized in terms of higher order finite differences: define

$$(\Delta_h^1 f)(x) = f(x+h) - f(x),$$

$$(\Delta_h^n f)(x) = \Delta_h^1 (\Delta_h^{n-1} f)(x) = \sum_{j=0}^n (-1)^{n-j} \binom{n}{j} f(x+jh)$$

then, for *n* integer such that s < n, we can take

$$\|f\|_{B^{s}_{1,\infty}} = \|f\|_{L^{1}} + \sup_{|h| \le 1} \frac{\|\Delta_{h}^{n} f\|_{L^{1}}}{|h|^{s}}.$$

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

$$X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon}) (Z_t - Z_{t-\epsilon}) + \epsilon b(X_{t-\epsilon})$$

 $|\mathbb{E}(\Delta_h^n \varphi(X_t))| \le |\mathbb{E}(\Delta_h^n \varphi(X_t^{\epsilon}))| + |\mathbb{E}(\Delta_h^n \varphi(X_t) - \Delta_h^n \varphi(X_t^{\epsilon}))|$ Write:

$$|\mathbb{E}(\Delta_h^n\varphi(X_t^{\epsilon}))| = |\int_{\mathbb{R}^d} \Delta_h^n\varphi(x)f_{X_t^{\epsilon}}(x)dx| = |\int_{\mathbb{R}^d} \varphi(x)\Delta_{-h}^n f_{X_t^{\epsilon}}(x)dx|.$$

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$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

$$X_t^{\epsilon} = X_{t-\epsilon} + \sigma(X_{t-\epsilon}) (Z_t - Z_{t-\epsilon}) + \epsilon b(X_{t-\epsilon})$$

 $|\mathbb{E}(\Delta_h^n \varphi(X_t))| \le |\mathbb{E}(\Delta_h^n \varphi(X_t^{\epsilon}))| + |\mathbb{E}(\Delta_h^n \varphi(X_t) - \Delta_h^n \varphi(X_t^{\epsilon}))|$ Write:

$$|\mathbb{E}(\Delta_h^n\varphi(X_t^{\epsilon}))| = |\int_{\mathbb{R}^d} \Delta_h^n\varphi(x)f_{X_t^{\epsilon}}(x)dx| = |\int_{\mathbb{R}^d} \varphi(x)\Delta_{-h}^n f_{X_t^{\epsilon}}(x)dx|.$$

Then

$$\|f_{X_t^{\epsilon}}\|_{B_{\infty,1}^{n}(\mathbb{R}^d)} = \|f_{X_t^{\epsilon}}\|_{L^1(\mathbb{R}^d)} + \sup_{|h| \leq 1} \frac{\|\Delta_h^n f_{X_t^{\epsilon}}\|_{L^1}}{|h|^{n-\delta}} \leq C(n,\delta)\epsilon^{-n/\alpha}.$$

Deduce:

$$\begin{aligned} |\mathbb{E}(\Delta_h^n \varphi(X_t))| &\leq C \|\varphi\|_{\infty} \epsilon^{-n/\alpha} \|h\|^n + |\mathbb{E}(\Delta_h^n \varphi(X_t) - \Delta_h^n \varphi(X_t^{\epsilon}))| \\ &\leq C \|\varphi\|_{\infty} \epsilon^{-n/\alpha} \|h\|^n + C \|\varphi\|_{C^{\eta}} \mathbb{E}\|X_t - X_t^{\epsilon}\|^{\eta}. \end{aligned}$$

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Estimate of $\mathbb{E} || X_t - X_t^{\epsilon} ||^{\eta}$ and conclusion:

For $\alpha \in [1,2)$, this is estimated by classical stochastic calculus:

$$\mathbb{E}\|X_t - X_t^{\epsilon}\|^{\beta} \leq C_{\beta}\left(\epsilon^{\beta(1+\theta_1)/\alpha} + \epsilon^{\beta(1+\theta_2/\alpha)}\right)$$

for all $\beta \in (0, \alpha)$. If b is θ_2 Hölder (or bounded with $\theta_2 = 0$) and σ is θ_1 Hölder. Set $\kappa = \min\{1 + \theta_1, \alpha + \theta_2\} \rightsquigarrow$

$$\begin{aligned} |\mathbb{E}(\Delta_h^n \varphi(X_t))| &\leq C \|\varphi\|_{C^{\eta}} \left(\epsilon^{-n/\alpha} \|h\|^n + \epsilon^{\eta \kappa/\alpha}\right) \\ &\leq C \|\varphi\|_{C^{\eta}} \|h\|^{\lambda_n}. \end{aligned}$$

with $\lambda_n \to \kappa \eta$, when $n \to \infty$. Use a generalization of the above Lemma $\rightsquigarrow X_t$ has a density in $B_{1,\infty}^s$ for any $s < \kappa - 1$.
Estimate of $\mathbb{E} ||X_t - X_t^{\epsilon}||^{\eta}$ and conclusion:

The case α ∈ (0, 1) is slightly more complicated:
X_t^ϵ = X_{t-ϵ} + σ(X_{t-ϵ})(Z_t - Z_{t-ϵ}) + ϵb(X_{t-ϵ}) is not a good approximation of X_t.

Estimate of $\mathbb{E} \| X_t - X_t^{\epsilon} \|^{\eta}$ and conclusion:

- The case α ∈ (0, 1) is slightly more complicated:
 X_t^ϵ = X_{t-ϵ} + σ(X_{t-ϵ})(Z_t Z_{t-ϵ}) + ϵb(X_{t-ϵ}) is not a good approximation of X_t.
- Set

 $Y_t = Z_t + t \int_{\|z\| \le 1} zm(dz), \ \tilde{b}(x) = b(x) - \sigma(x) \int_{\|z\| \le 1} zm(dz)$ and rewrite the equation as

$$X_t = x + \int_0^t \sigma(X_{s-}) dY_s + \int_0^t \tilde{b}(X_s) ds$$

Estimate of $\mathbb{E} \| X_t - X_t^{\epsilon} \|^{\eta}$ and conclusion:

The case α ∈ (0, 1) is slightly more complicated:
X_t^ϵ = X_{t-ϵ} + σ(X_{t-ϵ})(Z_t - Z_{t-ϵ}) + ϵb(X_{t-ϵ}) is not a good approximation of X_t.

Set

 $Y_t = Z_t + t \int_{\|z\| \le 1} zm(dz), \ \tilde{b}(x) = b(x) - \sigma(x) \int_{\|z\| \le 1} zm(dz)$ and rewrite the equation as

$$X_t = x + \int_0^t \sigma(X_{s-}) dY_s + \int_0^t \tilde{b}(X_s) ds$$

- ► We take V_t^{ϵ} which satisfies and set $V_t^{\epsilon} = X_{t-\epsilon} + \int_{t-\epsilon}^t \tilde{b}(V_s^{\epsilon}) ds$ $X_t^{\epsilon} = V_t^{\epsilon} + \sigma(X_{t-\epsilon})(Y_t - Y_{t-\epsilon})$
- ► Then, for $\beta < \alpha$, $\mathbb{E}\|X_t - X_t^{\epsilon}\|^{\beta} \le C_{\beta} \left(\epsilon^{\beta(1/\alpha + \theta_1)} + \epsilon^{\beta(1+\theta_2/\alpha)} + \epsilon^{\beta/(1-\theta_2)} \right)$

Estimate of $\mathbb{E} || X_t - X_t^{\epsilon} ||^{\eta}$ and conclusion:

We again have: $X_t^{\epsilon} = V_t^{\epsilon} + \sigma(X_{t-\epsilon})(Y_t - Y_{t-\epsilon})$ with V_t^{ϵ} which is $\mathcal{F}_{t-\epsilon}$ -measurable and such that, for $\beta < \alpha$,

$$\mathbb{E}\|X_t - X_t^{\epsilon}\|^{\beta} \leq C_{\beta} \left(\epsilon^{\beta(1/\alpha + \theta_1)} + \epsilon^{\beta(1+\theta_2/\alpha)} + \epsilon^{\beta/(1-\theta_2)}\right)$$

Similar argument as in the case $\alpha \in [1, 2)$ give a density in $B_{1,\infty}^s$ for any $s < (\kappa - 1)\alpha$.

Refinement when σ is not invertible everywhere: Write:

$$\begin{split} \left| \mathbb{E} \left(\frac{\Delta_h^n \phi(X_t)}{|\sigma^{-1}(X_t)|} \right) \right| &\leq \left| \mathbb{E} \left(\Delta_h^n \phi(X_t) \left[\frac{1}{|\sigma^{-1}(X_t)|} - \frac{1}{|\sigma^{-1}(X_{t-\epsilon})|} \right] \right) \right. \\ &+ \left| \mathbb{E} \left(\left[\Delta_h^n \phi(X_t) - \Delta_h^n \phi(X_t^{\epsilon}) \right] \frac{1}{|\sigma^{-1}(X_{t-\epsilon})|} \right) \right| \\ &+ \left| \mathbb{E} \left(\left[\Delta_h^n \phi(X_t^{\epsilon}) \right] \frac{1}{|\sigma^{-1}(X_{t-\epsilon})|} \right) \right|. \end{split}$$

Since

$$\mathbb{E}\left(\frac{\Delta_h^n\phi(X_t)}{|\sigma^{-1}(X_t)|}\right) = \int_{\mathbb{R}^d} \Delta_h^n\phi(x)\frac{1}{|\sigma^{-1}(x)|}f_{x_t}(dx)$$

Use the same ideas to obtain that $f_{X_t}(dx)/|\sigma^{-1}(x)|$ has a density in a Besov space.

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Refinement when σ is not invertible everywhere: Write:

$$\begin{split} \left| \mathbb{E} \left(\frac{\Delta_h^n \phi(X_t)}{|\sigma^{-1}(X_t)|} \right) \right| &\leq \left| \mathbb{E} \left(\Delta_h^n \phi(X_t) \left[\frac{1}{|\sigma^{-1}(X_t)|} - \frac{1}{|\sigma^{-1}(X_{t-\epsilon})|} \right] \right) \right. \\ &+ \left| \mathbb{E} \left(\left[\Delta_h^n \phi(X_t) - \Delta_h^n \phi(X_t^{\epsilon}) \right] \frac{1}{|\sigma^{-1}(X_{t-\epsilon})|} \right) \right| \\ &+ \left| \mathbb{E} \left(\left[\Delta_h^n \phi(X_t^{\epsilon}) \right] \frac{1}{|\sigma^{-1}(X_{t-\epsilon})|} \right) \right|. \end{split}$$

Since

$$\mathbb{E}\left(\frac{\Delta_h^n\phi(X_t)}{|\sigma^{-1}(X_t)|}\right) = \int_{\mathbb{R}^d} \Delta_h^n\phi(x)\frac{1}{|\sigma^{-1}(x)|}f_{x_t}(dx)$$

Use the same ideas to obtain that $f_{X_t}(dx)/|\sigma^{-1}(x)|$ has a density in a Besov space. This shows that f_{X_t} has a density on the set $\{x \in \mathbb{R}^d : \sigma(x) \text{ is invertible}\}.$ The result for $\alpha \in [1, 2)$:

Let $\sigma : \mathbb{R}^d \mapsto M_{d \times d}(\mathbb{R})$ and $b : \mathbb{R}^d \mapsto \mathbb{R}^d$ be measurable and bounded. Consider a $(\mathcal{F}_t)_{t \ge 0}$ -adapted càdlàg solution $(X_t)_{t \ge 0}$ to

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

where $(Z_t)_{t\geq 0}$ is a Lévy process with Lévy measure *m* satisfying (H_{α}) for some $\alpha \in [1, 2)$. Assume that $\sigma \in C^{\theta_1}(\mathbb{R}^d)$ for some $\theta_1 \in (0, 1)$, that *b* is measurable (then set $\theta_2 = 0$) or that $b \in C^{\theta_2}(\mathbb{R}^d)$ for some $\theta_2 \in (0, 1)$ and that $\kappa = \min\{1 + \theta_1, \alpha + \theta_2\} > 1$. Then for all t > 0, the law f_{X_t} of X_t has a density on the set $\{y \in \mathbb{R}^d : \sigma(y) \text{ invertible}\}$. Furthermore, for all $\gamma \in (0, \kappa - 1)$, $|\sigma^{-1}|^{-1}f_{X_t} \in B^{\gamma}_{1,\infty}(\mathbb{R}^d)$.

The result for $\alpha \in (0, 1)$:

Let $\sigma : \mathbb{R}^d \mapsto M_{d \times d}(\mathbb{R})$ and $b : \mathbb{R}^d \mapsto \mathbb{R}^d$ be measurable and bounded. Consider a $(\mathcal{F}_t)_{t \ge 0}$ -adapted càdlàg solution $(X_t)_{t \ge 0}$ to

$$X_t = x + \int_0^t \sigma(X_{s-}) dZ_s + \int_0^t b(X_s) ds$$

where $(Z_t)_{t\geq 0}$ is a Lévy process with Lévy measure *m* satisfying (H_{α}) for some $\alpha \in (0, 1)$. Assume that $\sigma \in C^{\theta_1}(\mathbb{R}^d)$ for some $\theta_1 \in (0, 1)$, that $\tilde{b} \in C^{\theta_2}(\mathbb{R}^d)$ for some $\theta_2 \in (1 - \alpha, 1)$, where $\tilde{b}(x) := b(x) - \sigma(x) \int_{\{|z| \leq 1\}} zm(dz)$ is the true drift coefficient and set $\kappa = \min\{1 + \alpha\theta_1, \alpha + \theta_2, \alpha/(1 - \theta_2)\} > 1$. Then for all t > 0, the law f_{X_t} of X_t has a density on the set $\{y \in \mathbb{R}^d : \sigma(y) \text{ invertible}\}$. Furthermore, for all $\gamma \in (0, (\kappa - 1)\alpha)$, $|\sigma^{-1}|^{-1}f_{X_t} \in B^{\gamma}_{1,\infty}(\mathbb{R}^d)$.

We have assumed

 $\begin{cases} (i) \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ (ii) \exists C > 0, \ \forall a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^2 m(dz) \le Ca^{2-\alpha}, \\ (iii) \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^d} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{cases}$

• (iii) is equivalent to $\exists c > 0, \forall a \in (0, 1], \forall |\zeta| = 1$:

$$\int_{\{|z|\leq a\}} \langle \zeta, z\rangle^2 \, m(dz) \geq ca^{2-\alpha}.$$

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We have assumed

(i)
$$\forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty,$$

(ii) $\exists C > 0, \ \forall a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^2 m(dz) \le Ca^{2-\alpha},$
(iii) $\exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^d} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}.$

► (iii) is equivalent to
$$\exists c > 0, \forall a \in (0, 1], \forall |\zeta| = 1$$
:
$$\int_{\{|z| \le a\}} \langle \zeta, z \rangle^2 m(dz) \ge ca^{2-\alpha}.$$

This can be satisfies by very rough measures. For instance:

$$m(A) = \int_0^\infty \mu(dr) \int_{S^{d-1}} \mathbf{1}_A(r\sigma) \lambda(d\sigma)$$

for λ nonnegative finite measure on S^{d-1} whose support contains a basis of \mathbb{R}^d and $\mu = \sum_{n \geq 1} n^{\alpha-1} \delta_1 / n$, where $\beta_n \geq 0$ and $\mu = \sum_{n \geq 1} n^{\alpha-1} \delta_1 / n$.

We have assumed

$$\begin{aligned} \text{(i)} \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ \text{(ii)} \exists C > 0, \ \forall \ a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^2 m(dz) \le Ca^{2-\alpha}, \\ \text{(iii)} \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^d} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{aligned}$$

▶ If we consider a α -stable process $(Y_t)_{t \ge 0}$ with $\alpha \in (1, 2)$,

$$\begin{cases} \widehat{f_{Y_t}}(\xi) := \mathbb{E}[\exp(i\langle \xi, Y_t \rangle)] = \exp(-t\Psi(\xi)), \\ \text{where} \quad \Psi(\xi) = \int_{\mathbb{R}^d} \left(1 - e^{i\langle \xi, z \rangle} + i\langle \xi, z \rangle\right) m(dz), \end{cases}$$

where $m(A) = \int_0^\infty r^{-\alpha-1} dr \int_{\mathbb{S}^{d-1}} \mathbb{I}_A(r\sigma)\lambda(d\sigma)$, (H_α) -(i)-(ii) clearly hold. If the support of λ contains a basis of \mathbb{R}^d , then (H_α) -(iii) is also OK.

 $Z_t = Y_t - t \int_{\|x\| \ge 1} xm(dx) \text{ satisfies all our assumptions.}$

We have assumed

$$\begin{aligned} \text{(i)} \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ \text{(ii)} \exists C > 0, \ \forall \ a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^2 m(dz) \le Ca^{2-\alpha}, \\ \text{(iii)} \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^d} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{aligned}$$

• If we consider a α -stable process $(Y_t)_{t\geq 0}$ with $\alpha \in (0,1)$,

$$\begin{cases} \widehat{f_{Y_t}}(\xi) := \mathbb{E}[\exp(i\langle \xi, Y_t \rangle)] = \exp(-t\Psi(\xi)), \\ \text{where} \quad \Psi(\xi) = \int_{\mathbb{R}^d} \left(1 - e^{i\langle \xi, z \rangle}\right) m(dz), \end{cases}$$

where $m(A) = \int_0^\infty r^{-\alpha-1} dr \int_{\mathbb{S}^{d-1}} \mathbb{I}_A(r\sigma)\lambda(d\sigma)$, (H_α) -(i)-(ii) clearly hold. If the support of λ contains a basis of \mathbb{R}^d , then (H_α) -(iii) is also OK.

• $Z_t = Y_t + t \int_{\|x\| \le 1} xm(dx)$ satisfies all our assumptions.

We have assumed $\begin{cases} (i) \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ (ii) \exists C > 0, \ \forall a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^{2} m(dz) \le Ca^{2-\alpha}, \\ (iii) \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^{d}} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{cases}$

(i) is not essential and can be replaced by

$$\int_{\{|z|\geq 1\}} m(dz) < \infty.$$

The conclusion is the same: existence of a density where σ is invertible but we loose the Besov smoothness

We have assumed

$$\begin{array}{l} \text{(i)} \forall \beta \in [0, \alpha), \ \int_{\{|z| \ge 1\}} |z|^{\beta} m(dz) < \infty, \\ \text{(ii)} \exists C > 0, \ \forall \ a \in (0, 1], \ \int_{\{|z| \le a\}} |z|^2 m(dz) \le Ca^{2-\alpha}, \\ \text{(iii)} \exists c > 0, \ \exists r > 0, \ \forall |\xi| \ge r, \ \int_{\mathbb{R}^d} (1 - \cos(\langle \xi, z \rangle)) m(dz) \ge c |\xi|^{\alpha}. \end{array}$$

It would more satisfactory to prove a result with (ii) and (iii) satisfied with possibly different values of α. This could be studied but the computations would be much longer.

Let u, p be the velocity and pressure of an incompressible fluid in a domain O:

 $\begin{cases} du + (-\nu\Delta u + \nabla p + (u \cdot \nabla)u)dt = fdt + d\eta, \ t \ge 0, \ x \in O, \\ \text{div } u = 0, \ t \ge 0, \ x \in O, \\ u = 0, \ \text{on } \partial O, \\ u(0) = u_0, \ x \in O. \end{cases}$

- ν is the viscosity and we take it equal to 1.
- The exterior forcing has two component. A deterministic one f, we take f = 0 and a random one of white noise type: $\eta = Q^{1/2} \sum_{i \in \mathbb{N}} \beta_i e_i = Q^{1/2} W.$
- The covariance operator describres the spatial smoothness of the noise

Let u, p be the velocity and pressure of an incompressible fluid in a domain O:

 $\begin{cases} du + (-\nu\Delta u + \nabla p + (u \cdot \nabla)u)dt = fdt + dW, \ t \ge 0, \ x \in O, \\ \text{div } u = 0, \ t \ge 0, \ x \in O, \\ u = 0, \ \text{on } \partial O, \\ u(0) = u_0, \ x \in O. \end{cases}$

- ▶ Project the equation on $H = \{u \in (L^2(O))^3; \text{ div } u = 0\}.$
- Define $A = \Delta u$, $D(A) = H^2(O) \cap H^1_0(0) \cap H$.
- \mathcal{P} is the projector onto H and $b(u) = \mathcal{P}$.

$$\begin{cases} du = (Au + b(u))dt + \sqrt{Q}dW, \\ u(0) = u_0 \in H. \end{cases}$$

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- Try to prove that finite dimensional projections of u have densities with respect to the Lebesgue measure.

$$\begin{cases} du = (Au + b(u))dt + \sqrt{Q}dW, \\ u(0) = u_0 \in H. \end{cases}$$

• It seems difficult to use Malliavin calculus. Indeed $D_s^h u(t) = \eta(t)$ where η is the solution of

$$\begin{cases} \frac{d}{dt}\eta = A\eta + b'(u) \cdot \eta, \\ \eta(0) = \sqrt{Q}h. \end{cases}$$

- We have no control on the Malliavin derivative of *u*.
- If the noise is sufficiently non degenerate, it is possible to use Malliavin on a truncated form of the Navier-Stokes equation and to obtain densities for the finite dimensional projections.
- ► Can we obtain something for degenerate noise ?

$$\begin{cases} du = (Au + b(u))dt + \sqrt{Q}dW, \\ u(0) = u_0 \in H. \end{cases}$$

► Let *F* be a finite dimensional subspace of *H* and π_F be the projector onto *F*.

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We investigate the quantity:

 $\int_{F} \Delta_{n}^{h} \varphi(z) d\nu_{F}(z) = \mathbb{E}(\Delta_{n}^{h} \varphi(\pi_{F} u(1)))$

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• Introduce u^{ϵ} :

$$\begin{cases} u^{\epsilon}(t) = u(t), t \leq 1 - \epsilon, \\ (I - \pi_F)u^{\epsilon}(t) = (I - \pi_F)u(t), t \geq 1 - \epsilon, \\ d\pi_F u^{\epsilon} = \pi_F A u^{\epsilon} + \pi_F \sqrt{Q} dW, t \geq 1 - \epsilon. \end{cases}$$

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$$u(1) = e^{\epsilon A}u(1 - \epsilon) + \int_{1 - \epsilon}^{1} e^{A(1 - s)}b(u(s))ds + \int_{1 - \epsilon}^{1} e^{A(1 - s)}\sqrt{Q}dW(s)$$

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$$u^{\epsilon}(1) = e^{\epsilon A}u(1 - \epsilon) + \int_{1 - \epsilon}^{1} e^{A(1 - s)}\sqrt{Q}dW(s)$$

► Since $\mathbb{E}(|\pi_F b(u)|)$ is bounded. It is easy to check that $\mathbb{E}(|\pi_F u(1) - \pi_F u^{\epsilon}(1)|) \le C_1 \epsilon$.

We then write, assuming that ker $Q = \{0\}$:

 $\mathbb{E}(\Delta_n^h \varphi(u(1))) = \mathbb{E}(\Delta_n^h \varphi(u(1)) - \Delta_n^h \varphi(u^{\epsilon}(1)))$

 $+\mathbb{E}(\Delta_n^h \varphi(u^{\epsilon}(1)+h)-\Delta_n^h \varphi(u^{\epsilon}(1)))$

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for $\epsilon = |h|^{\frac{2n}{2\alpha+n}}$.

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for $\epsilon = |h|^{\frac{2n}{2\alpha+n}}$. We deduce that u(1) has a density in $B_{1,\infty}^s(F)$ for $s < \frac{2\alpha n}{2\alpha+n} - \alpha \to \alpha$ when $n \to \infty$.

Theorem: Consider the stochastic Navier-Stokes equations, assume that $ker \ Q = \{0\}$ then for any finite dimensional space $F \subset H$ and any solution u of the martingale problem (limit of some Galerkin approximation), $\pi_F u(1)$ has a density with respect to the Lebesgue measure in $B_{1,\infty}^{\gamma}(F)$ for any $\gamma < 1$ and in $L^p(F)$ for any $1 \leq p < d/d - 1$.
The stochastic Navier-Stokes equations in dimension 3

A stationary solution has more regularity property (Flandoli & Romito):

 $\mathbb{E}\left(|\nabla u_{\mathcal{S}}|^2\right) < \infty$

This allow to improve the approximation of u by u^{ϵ} :

$$u^{\epsilon}(1) = e^{\epsilon A}u(1-\epsilon) + \int_{1-\epsilon}^{1} e^{A(1-s)}b(e^{A(s-1+\epsilon)}u(1-\epsilon))ds + \int_{1-\epsilon}^{1} e^{A(1-s)}\sqrt{Q}dW(s)$$

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Theorem: Consider the stochastic Navier-Stokes equations, assume that $ker \ Q = \{0\}$ then for any finite dimensional space $F \subset H$ and any stationary solution u of the martingale problem (limit of some Galerkin approximation), $\pi_F u(1)$ has a density with respect to the Lebesgue measure in $B_{1,\infty}^{\gamma}(F)$ for any $\gamma < 2$ and in $W^{1,p}(F)$ for any $1 \le p < d/d - 1$ or in $L^p(F)$ for any $1 \le p < d/d - 2$.

The stochastic Navier-Stokes equations in dimension 3

Remark

• This together with a result of Shirikyan implies that the densities are positive.

- Can we extend this result to the hypoelliptic case ?
- Can we obtain more regularity ?